# Photogrammetry Measurements of a **Time-Projection Chamber**

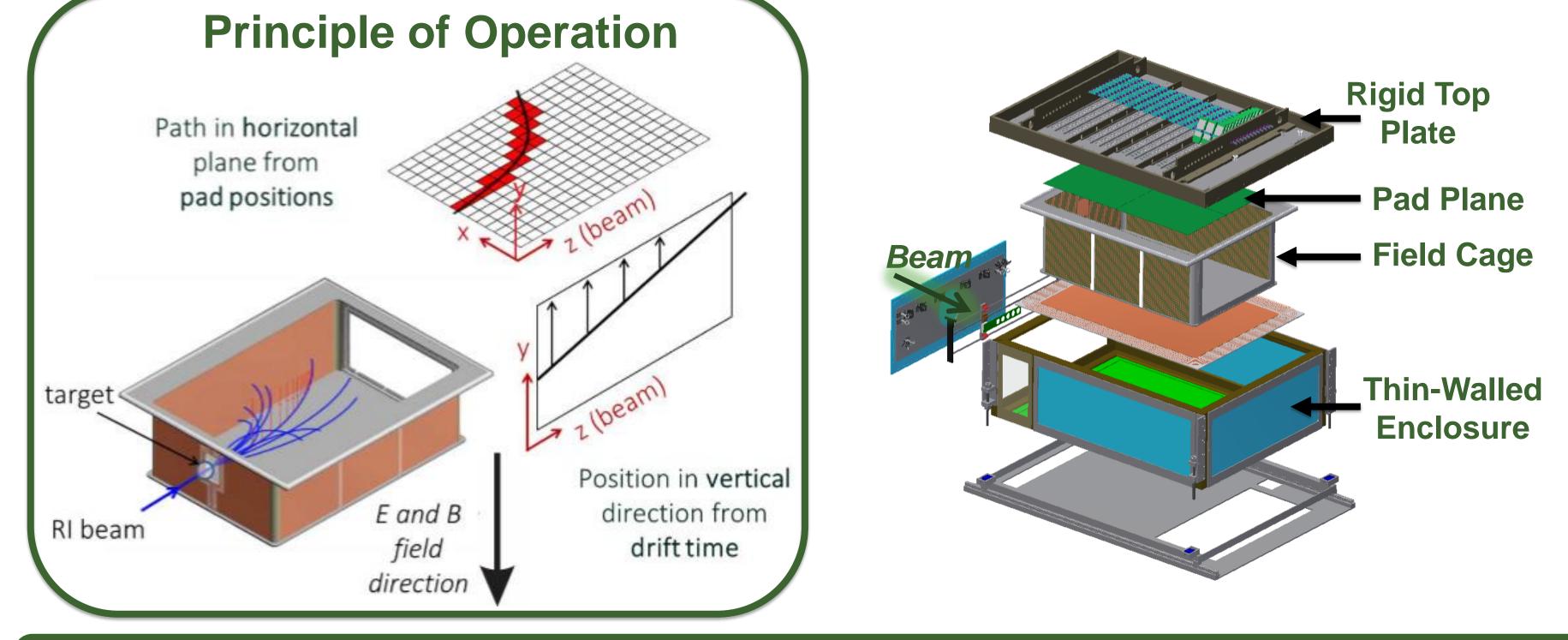
Benjamin Brophy<sup>1</sup>, J. Estee<sup>1</sup>, A. McIntosh<sup>2</sup>, M. Kurata-Nishimura<sup>3</sup>, R. Shane<sup>1</sup>, J. Barney<sup>1</sup>, T. Isobe<sup>3</sup>, W. G. Lynch<sup>1</sup>, T. Murakami<sup>4</sup>, H. Otsu<sup>3</sup>, M.B. Tsang<sup>1</sup>, S. Yennello<sup>2</sup> 1 NSCL and Department of Physics and Astronomy, Michigan State University, East Lansing, MI, 48824 2 Cyclotron Institute, Texas A&M University, College Station, TX 77843 3 RIKEN Nishina Center, Hirosawa 2-1, Wako, Saitama 351-0198, Japan 4 Department of Physics, Kyoto University, Kita-shirakawa, Kyoto 606-8502, Japan

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## **S**π**RIT** Time-Projection Chamber

- "SAMURAI Pion-Reconstruction and Ion-Tracker"
- Motivation
  - Nuclear equation of state
  - Implications to neutron stars
- Detects charged particles as they excite gas in chamber
- Can reconstruct path and identify particles based on known interaction with electric and magnetic fields
- Constructed at NSCL
- Shipped to RIKEN in Japan in 2014



#### **Importance of Precision Measurements**

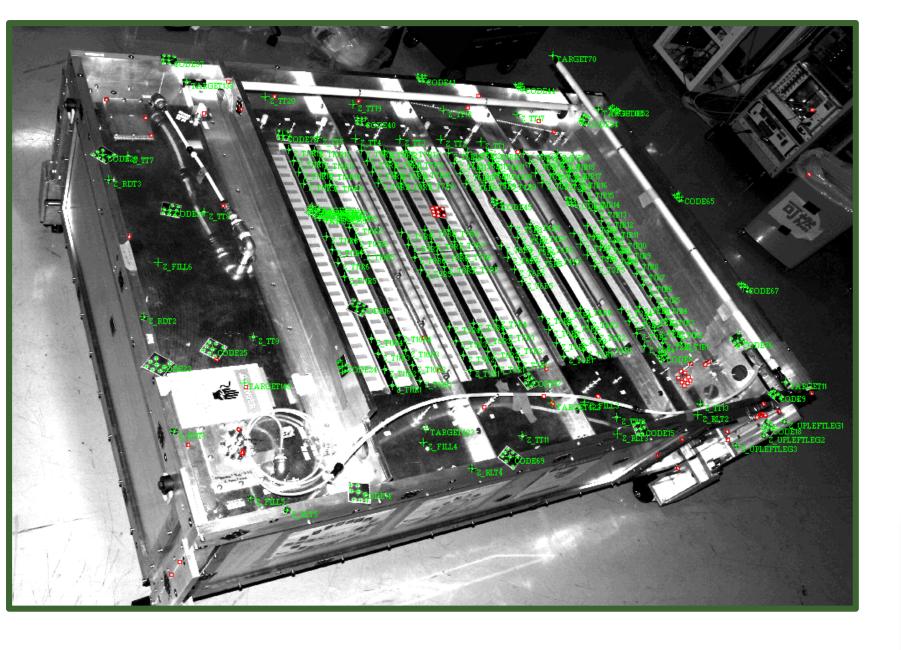
- Damage in shipment to Japan?
- Interested in micron scale precision
- Exact locations of internal components
- Flatness of surfaces
- Sagging of heavy structural components
- Field cage alignment & angle of electric field
- Symmetries of TPC

# **Parts of S**πRIT

- Field Cage: Defines uniform electric field, and contains detector gas.
- Rigid Top Plate: Primary structural member, reinforced with ribs. Holds pad plane and wire planes.
- Pad Plane: Mounted to bottom of top plate. Used to measure particle ionization tracks
- Thin-Walled Enclosure: Protects internal components, seals insulation gas volume, and supports pad plane while allowing particles to continue on to ancillary detectors.

# Photogrammetry

- Calibrated camera system from Geodetic
- Multiple photographs of an object can be reconstructed to make 3-D measurements
- Accurate to <100 micrometer.
- Codes placed onto object 4 per image needed for orientation
- Retro-reflective targets placed on points of interest
  - » Field cage walls

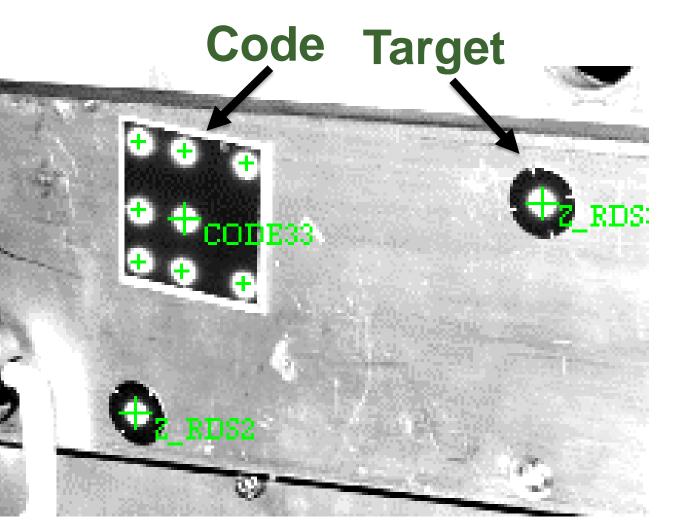


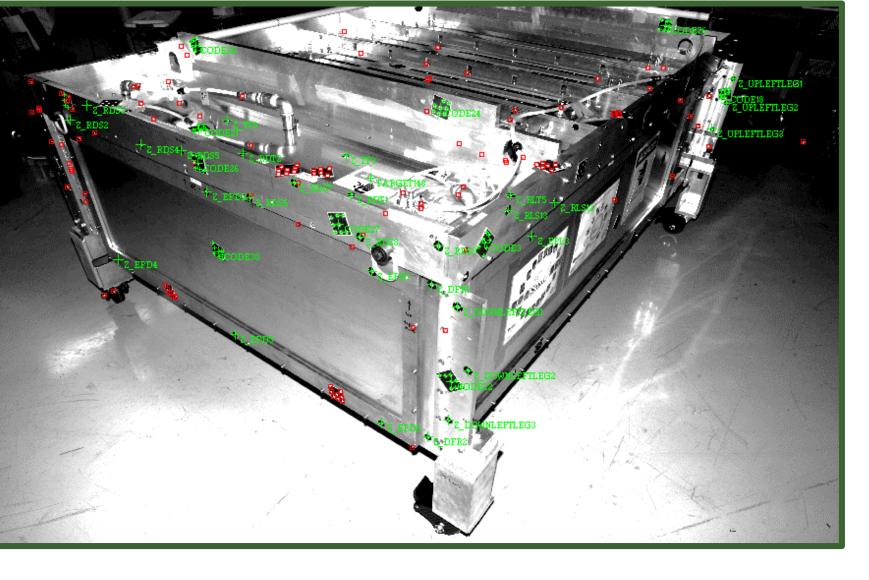
#### **Measurements with V-STARS Software**

- Set size, shape, and brightness parameters to identify points
- Filter out "flash points"
- Run bundle using STAR <u>Self-Calibration</u>, <u>Triangulation</u> <u>And</u> <u>Resection</u>
- Construct planes from points
- Construct points, axes from intersection of planes

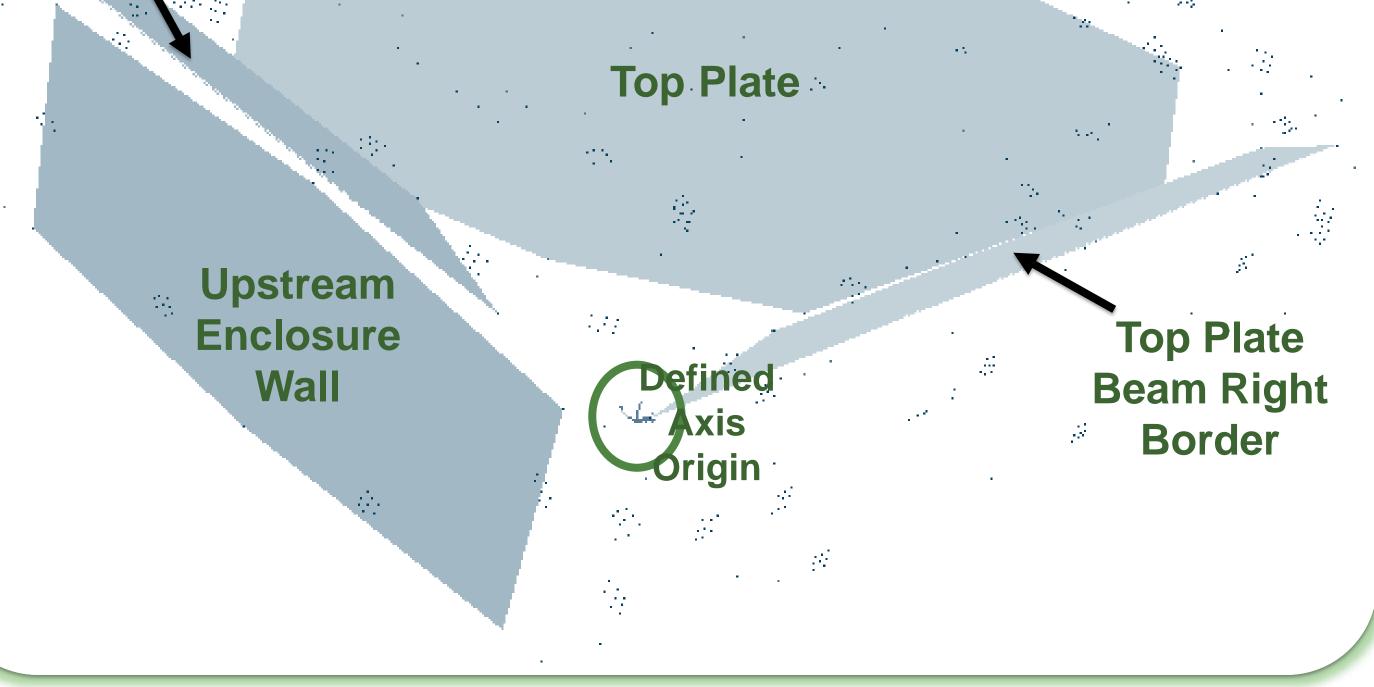


- Top plate
- Enclosure
- Photography concerns field of view (50deg), focusing, exposure
- Triangulation find point position across individual pictures
- Resection determination of camera location





- Images above and left analyzed by V-STARS
- Identified targets and codes with green crosses
- Red crosses are failed matches either the software failed to match the point with others, or they are reflective spots but not targets



Images above and right – black dots are all identified points displayed in 3-D. Constructed planes on top plate, downstream face of enclosure, 3 top plate walls

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