

MSUCP-7

MISTIC GENERAL ORBIT
CODE

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Introduction

A computer routine is described which integrates the relativistic equations of motion for particles moving in accelerator type orbits. The routine is designed for use in the study of sector focused cyclotrons; in addition it is adaptable to a considerable range of other orbit tracking problems. The coding is for computers of the basic Illiac type (1024 word fast memory; no auxiliary memory). The program requires 523 memory locations for storage of instructions and computed quantities leaving 501 locations for storage of a table of cosines (typically 25 locations required) and for storage of magnetic field information. The relatively large block of field information (typically 476 locations) allows a carefully detailed description of the field. At the expense of more awkward operation an additional 90 field storage locations can be provided by overwriting portions of the program as described in Appendix F.

While written specifically for the Illiac class of computers the routine could presumably be transcribed to other logically similar computers in a fairly direct way. Of particular interest in this regard would be computers which, like the Illiac, have relatively small memories, since (1) the number of instructions for this routine is considerably smaller than other comparable routines of which we are aware and (2) the storage of the field as tables of Fourier coefficients gives both compact storage and detailed representation of the field features of dominant importance in determining particle trajectories.

In order to use or transcribe this program a moderate familiarity with programming procedures for Illiac type computers is necessary. The programming manual for the MISTIC¹.

¹. MISTIC Programming Manual, 2nd Edition, Michigan State University Computer Laboratory Publication (Sept. 1959).

presents such a description in more than adequate detail. In particular, in order to use this program, a general familiarity with computer operations (such as is presented in chapters 1, 2 and 3 of the MISTIC manual) and a knowledge of the Decimal Order Input routine (chapter 4 of the MISTIC manual) are adequate. In this report the actual MISTIC order pairs are presented in section VIII - with the exception of this section effort has been made to minimize specific reference to MISTIC language, hopefully thereby making the earlier sections more understandable for those not familiar with the MISTIC.

I. Equations of Motion

The equations of motion are written in cylindrical coordinates as a set of linear first order coupled equations with the azimuthal angle θ as the independent variable. The equations of motion in this form are:

$$\begin{aligned} (1) \quad dz/d\theta &= rp_z/Q \\ (2) \quad dp_z/d\theta &= zr \partial B/\partial r - (zp_r/Q) \partial B/\partial \theta \\ (3) \quad dr/d\theta &= rp_r/Q \\ (4) \quad dp_r/d\theta &= Q - rB + (zp_z/Q) \partial B/\partial \theta \\ (5) \quad d\phi/d\theta &= (\gamma r/Q) - 1 \end{aligned}$$

where z , r , p_z and p_r are the axial and radial positions and momenta of the particle, Q is the azimuthal component of momentum ($Q^2 = \gamma^2 - p_r^2 - p_z^2 - 1$), γ is the total energy of the particle in rest mass units, and ϕ is the difference in time for the actual particle to reach angle θ and that required for a fictitious particle moving with uniform angular velocity of ω_{rf} to reach the same angle, the time difference being measured in units². in which the r-f period is 2π . When the "median plane overwrite" is employed, equations (1) and (2), the final term in equation (4), and the p_z factor in Q are dropped.

The equations are exact for motion in the median plane and are accurate to first order terms in z for off median plane motion. The equations would be accurate thru second order terms in z if B in eq. 4 were replaced by $(B - z^2 \nabla^2 B / 2)$.

The median plane magnetic field is specified in the form:

$$(6) \quad B(r, \theta) = B_0(r) + \sum_{i=1}^H [H_i(r) \cos iN\theta + G_i(r) \sin iN\theta] + \sum_{i=1}^h [h_i(r) \cos i\theta + g_i(r) \sin i\theta].$$

². With this choice of units, ϕ is also the angular difference in phase between particle and r-f. Note that positive ϕ means particle takes longer to reach a given angle and hence is lagging behind r-f.

The $B_0(r)$ and the first sum in (6) are referred to as the "main field", the second sum is referred to as the "imperfection field". The functions $B_0(r)$, $H_1(r)$, etc. are specified by numerical tables giving the values of the function at a sequence of equally spaced radius points (r_0 , $r_0 + \Delta r$, $r_0 + 2\Delta r$, ...) with the additional restriction that r_0 (the first r at which the functions are given) must be equal to $\eta\Delta r$ where η is an integer. The quantities B and $\partial B/\partial\theta$ are determined by evaluating (6) and its θ derivative equation at the four nearest radius points to the value desired and performing a four point central polynomial interpolation in these values. The $\partial B/\partial r$ is obtained by differentiation of the polynomial for B . If at any point the orbit lies so close to the edge of the given field information that the central interpolation process is invalid, the computer prints information as described in section VI and stops. The number of sectors, N , which appears in eq. (6) is internally set to be 3 (to change N , see Appendix B).

The routine will simulate acceleration by increasing γ at one or both of two arbitrarily specified azimuths by an amount:

$$(7) \quad \Delta\gamma = (1/2) (\Delta K/E_0) \cos \phi(\theta).$$

The $\cos \phi$ in equation (7) is computed accurate to fourth order terms in ϕ . With minor modification, as described in Appendix E, the routine will omit the $\cos \phi$ factor from (7). With a different modification, also described in Appendix E, the energy gain can be distributed over the full circumference rather than being localized at particular azimuths.

The routine will track orbits in either direction with respect to the θ in eq. (6). Runs designated "forward" go in the negative θ direction corresponding to the direction of rotation of a positive particle in a positive magnetic field in a right handed coordinate system. For convenience in making phase plots, the signs of p_r and p_z in the equations

are reversed for "backward" runs. As a result of this, if the final point of a forward run is used as the initial point of a backward run, identically the same lines of output will be obtained (except for round off errors) but in inverse order. A backward run is in this sense, then, simply determining where a forward moving particle has come from.

II. Units, Scaling, and Program Stops

In setting up data and parameters for the routine an appropriate set of units must be employed such that the numerical relationships indicated by equations (1) thru (7) are in correspondence with the equations of motion for the particle being considered. For the case of the f-f cyclotron it is convenient to numerically specify lengths in units of c/ω_{rf} , momenta in units of m_0c , and magnetic fields in units of $4\omega_{rf}m_0/q$, where ω_{rf} is the frequency of the accelerating voltage, m_0 and q are the rest mass and charge of the accelerated particle, and c is the velocity of light. The factor four is inserted in the field unit so that the B's, H's, G's, h's and g's describing the field will be numerically less than 1/2 for normal fields as is required by scaling used in the routine.

Units involving ω_{rf} are usually internally computed by the routine in a manner such that ω_{rf} is taken to be $eB_0(0)/m_0$. In this case, the field unit becomes simply $4B_0(0)$ which is the scaling of the normally used B's, H's, G's, etc. obtained from the Mystic Pole Code.³ With this scaling the field will of course necessarily be isochronous close to $r=0$ (to change to arbitrary ω_{rf} , see Appendix J).

For input, the parameters q and m_0 describing the accelerated particle are given as an integer q' ($q = q'e$ where e is the magnitude of the electronic charge) and a fraction m_0' (where m_0' is the mass of the neutral atom in atomic mass units and must be < 100). The central magnetic field is input via the pair of quantities $B_0(0)$ in "volts"⁴ and a "volts" to weber/m² conversion factor.

³. A Mystic Routine for Conversion of Rectangular Coordinate Field Data to Tables of Fourier Coefficients, H.G. Blosser, MSUCP report (in preparation).

⁴. An arbitrary unit related to the MSU field measuring equipment. $B_0(0)$ in volts is the 1st number on Pole Code output tapes.

The rest energy of the accelerated particle is internally computed from the charge and mass data ($E_0 = m_0'c^2 - q'm_{ec}^2$). For particles with $E_0 < 10^9$ ev, kinetic energies are input in units of 10^9 ev, if $E_0 < 10^{10}$ ev, kinetic energies are in units of 10^{10} ev, etc. The quantity γ is internally computed by the routine from the kinetic and rest energies.

Tests on the numerical magnitude of various quantities are employed in the code to protect against the possibility of overflow. Principal among these are tests which require r , z , B , $\partial B/\partial r$ and $\partial B/\partial \theta$ to be at all times less than $1/2$ in magnitude and a test which requires z to be always both less than r and less than $1/8$ in magnitude. A list of program stops and their significance is given in Table I.

Table I. Orbit Code Stops. For each stop the decimal location is given, with "l" or "r" signifying the left or right order, followed by the base 16 location in parenthesis, followed by the stop order and addresses.

"Load B Routine" Stops.

- r 071(047) - 0F001: Some B_0 , H_i , G_i , h_i or g_i on data tape has magnitude $\geq 1/2$.
- l 088(058) - 20058: All B_0 's, H's and G's are loaded. Ready for h's and g's if any
- r 090(05K) - 243F7: All h's and g's (if any) loaded. Ready for main program.

Main Program Stops

- r 001(001) - 243F7: DOI stop-occurs during loading of program tape when all sections except "Parameter Routine" have been loaded.
- l 984(3J8) - 2438J: Program tape loaded or run completed - ready for new run.
- l 1019(3LS) -SF000: Reader sum check fails (hexadecimal tapes only).
- r 396(18N) - 4F037: Memory sum check fails.
- l 336(150) - 6601N: $|r_{pr}/Q| \geq 1$.
- r 339(153) - 6601N: $|r_{pz}/Q| \geq 1$.
- r 343(157) - 6600F: $K > E_0$.
- l 346(15K) - 6601N: $|(1/4)d\phi/d\theta| \geq 1$.
- l 353(161) - 66006: $|z| \geq |r|$
- l 355(163) - 66020: $|dp_z/d\theta| \geq 1$.
- l 362(16K) - 66020: $|z_{pz}(\partial B/\partial \theta)/4Q| \geq 1$
- r 365(16J) - 66000: $|dpr/d\theta| \geq 1$.
- l 368(170) - KK001: $|r| \geq 1/2$.
- r 144(090) - SF001: $|\Sigma B - G_x \sin x\theta| \geq 1/2$.
- r 147(093) - SF002: $|\Sigma B + H_x \cos x\theta| \geq 1/2$.
- r 153(099) - SF003: $|\Sigma B_\theta + N H_x \sin x\theta| \geq 1/2$.
- r 156(09N) - SF004: $|\Sigma B_\theta + N G_x \cos x\theta| \geq 1/2$.
- r 059(03S) - 66002: $1+p_r^2+p_z^2 \geq \gamma^2$

III. Operation of the Routine

Use of the routine begins with loading of magnetic field information, the numerical values being arranged on a data tape the format of which is described in Section IV. A special routine is employed ("Load B Routine") which, after the fields are loaded, is overwritten by the main program. After loading of the main program, parameters giving the initial values of the several variables are loaded as described in section V and the integration proceeds. A basic sixteen Runge-Kutta steps per sector are employed (to change this number see Appendix C.) and the quantities z , p_z , r , p_r , $\phi/4$, K , and $(1/64)\Sigma r^5$ are printed out periodically, the number of R-K steps between prints being given by one of the parameters. The run proceeds in this manner for a number of prints also specified by an input parameter. (Note: the code begins by printing out initial conditions and counts this as 1 print. To obtain new information a minimum of two prints must be requested.)

Immediately after the second and each subsequent print the code performs a sum check of memory locations 55 thru 985 (with locations involving variable addresses excepted) and stops if the sum is improper. On the first run after loading a set of fields, the sum will of necessity be improper and the code will stop after the second print. Restarting with a white switch start will set the sum comparison to the proper value after which no more such stops will normally occur unless fields or code are modified. If such a stop does occur, memory failure is indicated and the program and fields should be reloaded. For the use of maintenance personnel a ten digit sexadecimal word is punched when a sum

⁵. The quantity $(1/64)\Sigma r$ is a scaled $(1/64)$ sum of the values of r on every previous R-K step, from the beginning of the run. On long runs this quantity will periodically overflow and the values suddenly decrease by minus two. If the proper number of twos, as indicated by the successive jumps, is added to the value printed, the correct sum is obtained.

check stop occurs. This word should be zero; the extent to which it fails to be zero indicates the error in the sum and hence pin points the memory stage involved in the failure.

If several runs are to be made with the same magnetic field it is suggested that after an initial run has been made to set the sum check comparison, a sexadecimal tape of the program and fields be prepared using Mystic library routine X-16S. The fields and program can then be loaded with greatly enhanced speed on subsequent runs and in addition a double check on reader errors is provided. (Tapes produced by X-16S themselves contain a reader sum check; the sum check included in the program provides a second test).

When a given run terminates, the code returns to a position ready to load new parameters and stops. If parameters for a series of runs are on the same data tape the black switch can be placed on ignore and the routine will proceed automatically through the series (see section V for details and limitations on this procedure).

If no axial motion is included in a particular run the median plane overwrite should be employed and is loaded with the white switch prior to loading of the parameters. This overwrite reduces the running time by 40% and in addition prevents round off errors from building up spurious z motion.

IV. Data Tape Format

The data tape consists of a set of numbers describing the arrangement and characteristics of the field and the accelerated particle, followed by the field information itself. In cases where the quantity of information on the field data tape exceeds the available memory space, the Load B Routine can be instructed to select an arbitrary section of the field thereby avoiding the necessity of having several tapes containing various sections of a given field. The arrangement of the data tape is as follows (in this and following sections the format of the Illiac Decimal Order Input routine is used):

00 18 K	Storage Directive
00 F 00 a F:	a is number of entries <u>to be loaded in memory</u> for <u>each</u> of the functions B_0, H_1, G_1, \dots
00 F 00 H F:	H is number of harmonics in the main field to be loaded in memory. $H \geq 1$.
00 F 00 h F:	h is number of harmonics in imperfection field to be loaded in memory. $h \geq 0$.
00 dF 00 F:	B_0 's, H's, G's appear on data tape as sign plus d decimal digits.
00 F 00 b F:	b is number of entries <u>on the data tape for each</u> of the functions B_0, H_1, G_1, \dots
00 F 00 α F:	α is no. of entries on the data tape which are skipped for each of the functions B_0, H_1, G_1, \dots before starting to load the specified <u>a</u> entries. ($b \geq \alpha + a$)
00 F 00 β F	$r_{\min.} = \beta \Delta r$ is the smallest r value for which the B_0 's, H's and G's are <u>loaded in the memory</u> . Since $r_0 = \eta \Delta r$ is first r value for which the functions are given on the data tape, $\beta = \alpha + \eta$. Also, always, β must be integer greater than or equal to minus one. (Note: $\beta = -1$ is given in DOI format by LL 4095F LL 4095F.

00 33K Storage Directive

00 F 00 $[\xi/10]J$: $B(\text{weber}/\text{m}^2) = \xi \cdot B(\text{volts})$

00 F 00 $[B_0(0)/10]J$: $B_0(0)$ is the measured central field
in volts ($B_0(0)/10$ is first number
on Pole Code output tapes).

00 F 00 $[\lambda/4]J$: Flutter field (H's, G's, h's and g's
but not B_0 's) is multiplied by λ .
($\lambda/4$ is first number on Isochronous
Code output tapes).

00 F 00 $[\Delta r]J$: Δr is the spacing of B's, H's, etc.
in units of inches in the model magnet.

00 F 00 s J: s is the scale factor of the model
magnet i.e. $s=1/6, 1/5, 8.75/64$, etc.

00 F 00 q'F: the charge of the accelerated particle
is $q=q'e$.

00 F 00 $[m'_0/100]J$: m'_0 is the mass in atomic mass units of
the neutral atom from which the acceler-
ated particle was produced.

24 95 N Transfer to load B routine; can be
26 95N if B_0 's, H's, G's, etc. are on
same tape.

Field data (each quantity typed as sign plus d decimal digits):

$B_0(\eta\Delta r), B_0([\eta+1] \Delta r), \dots, B_0([\eta+a-1] \Delta r), H_1([\eta\Delta r] \Delta r), \dots$
 $\dots, H_1([\eta+a-1] \Delta r), G_1(\eta\Delta r), \dots, G_1([\eta+a-1] \Delta r), H_2(\eta\Delta r), \dots$
 $\dots, G_H([\eta+a-1] \Delta r).$

Following loading of the main field the computer will stop. If the imperfection field is on a different tape this tape is placed under the reader and operation resumed with the black switch. The imperfection field is in the same format as the main field viz:

$h_1(\eta\Delta r), \dots, h_1([\eta+a-1] \Delta r), g_1(\eta\Delta r), \dots, g_h([\eta+a-1] \Delta r).$

Following loading of the imperfection field the computer again stops, after which restarting with the black switch will cause the main program to load (if no imperfection field is used, i.e. if $h=0$, two black switch starts are required to cause the main program to load.) The main program tape as mentioned previously is preset for 48 R-K steps per revolution integration and contains the required table of cosines for this number of R-K steps. This cosine table occupies 25 memory locations - hence in this case, unless the special procedures described in Appendix F have been employed, the total number of B's, H's, G's, h's, and g's loaded in the memory must not exceed 476, i.e., in terms of the parameters, $[2(H+h) + 1] a \leq 476$.

V. Parameters:

Initial conditions and run parameters are stored at two places in the program the first being in locations 4 thru 16 and the second in locations 986 thru 998. The sequence 4 thru 16 are the actual initial conditions used by the code; these locations are also used for running storage of the various variables and hence are continually changing as the integration process proceeds. The sequence 986 thru 998 are employed as "master" parameters, i.e. at the end of any run (and initially after loading of the complete program tape) 986 thru 998 are copied into 4 thru 16. Table II is a list of various parameters including their location and significance. Also, for each parameter, the value preset in the program tape is included in parentheses.

To run a series of runs the sequence 986 thru 998 is set to the values which apply most often to the sequence; then for the individual runs only those parameters which differ from the master values need be set, the revised values being stored in the sequence 4 thru 16. Note that 986 thru 998 are not normally copied into 4 thru 16 until the end of a run; changes in 986 thru 998 will therefore normally not effect the first run following the change. (Changes in 986 thru 998 can be caused to effect the first run if desired, by using the white switch and DOI, as discussed below, to make the changes with the changes terminated by the special transfer directive 26977N. This termination, causes control to be transferred directly to the routine which copies 986 thru 998 into 4 thru 16; after doing this the computer will stop at the normal end of run stop, ready to pick up additional parameters, if any, in the normal manner.)

Two routines are included in the program for the loading of parameters. These routines can be employed in a variety of fashions to change either the master parameters or the

Table II: RUN PARAMETERS

Run Location	Master Location	Parameter Function (Preset Value in Parenthesis)
004	986	Z_0 =value of Z at initial θ in c/ω_{rf} units. ($=10^{-5}$)
005	987	p_{z0} =value of p_z at initial θ in m_0c units. ($=0$)
006	988	r_0 =value of r at initial θ in c/ω_{rf} units. ($=.25$)
007	989	p_{r0} =value of p_r at initial θ in m_0c units. ($=.085$)
008	990	$\phi_0/4$ =value of $\phi/4$ at initial θ in radians. ($=0$)
009	991	K_0 =value of K at initial θ . Units of K same as units of E_0 below. ($=.028$)
010	992	$[1/64]\Sigma r$ - initial value irrelevant - automatically set to zero by code.
011	993	δK - K is increased by $[\delta K/2] \cos \phi$ at gap crossing - units of δK same as E_0 . ($=.00028$)
012	994	$\theta_1 \times 2^{-10}$ where θ_1 is integer giving no. of R-K steps at end of which gap one is crossed. Cell must be <u>exactly</u> $\theta_1 \times 2^{-10}$ to give gap crossing; hence use DOI integer input to set. Examples: $\theta_1=4 \rightarrow 00\ 8F\ 00F$, $\theta_1=0 \rightarrow 00\ F\ 00\ F$, no gap crossing $\rightarrow 00\ F\ 00\ xF$ where $x[\text{modulo } 2^{20}] \neq 0$. ($00\ F\ 00\ 1F$)
013	995	Same as θ_1 except gap two.
014	996	E_0 -rest energy of particle - normally set by load B routine in units of 10^n ev where n is smallest integer which makes $E_0 < 1$. Examples: protons $\rightarrow E_0=.938$ ---, deuterons $\rightarrow E_0=.187$ ---. Preset value may be overwritten if desired, with units arbitrary, except $E_0 < 1$. Note: see K and δK descriptions above.
015	997	$[-1+R_p \times 2^{-39}]$ where R_p is no. of R-K steps between prints of results. Note: since R_p is integer, use DOI integer input to change; "minus one" implies $80\ F\ 00\ R_p\ F$. ($R_p=16$)
016	998	$[-1+R_r \times 2^{-39}]$ where R_r is no. of prints per run. Value of R_r in these locations is irrelevant when "New Parameter Routine" is in use since that routine independently sets R_r in location 016 as last step before starting run. Note that 998 still is used to set -1 in 016.

run parameters or both. The first of these routines is specially written to provide for the loading of fractions with minimum tape preparation. This routine also has a special termination feature as described further below which is used to select forward or backward integration of the orbits. The second routine is the standard Decimal Order Input which can of course be used to change the contents of any memory cell following conventional DOI procedure.

After loading of the program tape or after completing a run, the computer stops (if the black switch is not on ignore) on a 24 order in location 984 (3J8), this order being the normal end of run stop. At this point restarting with the white switch will transfer to the DOI whereas restarting with the black switch transfers to the "Special Input Routine". Since the Special Input Routine, as mentioned above, sets a number of orders in the code to provide for either forward or backward integration, it is necessary, if the DOI input is employed, to also go through the special routine even if the routine is used for nothing more than specifying the length of the run and whether it is forward or backward - this is accomplished by terminating the DOI portion of the parameter tape with a transfer to the special routine (26909N). Note that a number of the parameters, i.e. θ_1 , θ_2 , R_p , etc., are of integer type and, since the new parameter routine is designed only for the loading of fractions, it is always necessary when changing these quantities to employ the DOI. When using the DOI, prepare parameters in standard DOI format as described in the Mystic manual.¹

The Special Input Routine differs from the DOI in that fifth hole characters on the input tape are employed as signals to denote the termination of numbers; the number of digits in any quantity can then be arbitrary. All quantities on the tape except the termination symbol, discussed

in the following paragraph, consist of address-fraction pairs, the address portion of the pair telling where the fraction is to be stored in the memory. In preparing the tape the address is typed first as a decimal integer (at least one and less than 13 digits interpreted modulo 4096) followed by some fifth hole character, this character denoting the end of the address. Next the fraction is typed with or without sign (if sign is omitted the fraction is interpreted as positive) and with optional number of digits (at least one and less than 13) and again with any fifth hole character denoting the termination of the fraction. Always, the fraction is interpreted as having decimal point immediately in front of the first digit regardless of the number of digits typed. The fifth hole character at the end of the fraction signals the routine to store the fraction in the previously loaded address and prepare for a new address-fraction pair. This process is continued for as many pairs as desired.

Finally, when all desired parameters have been set, the run is started by typing a decimal integer specifying the number of prints desired in the run, the integer being followed directly by either an "F" or a "K" depending on whether the run is to be in the Forward or bacKward direction. Whenever such a group of characters (i.e. one or more digits followed directly by an F or K) appears on the tape, the routine sets the necessary orders in the program, transfers to the proper section of the code, and proceeds with the run. A "4F" for example typed on the tape will cause the code to print four times (one of the times being initial conditions) integrating in the forward direction between prints. Similarly "26K" would give 26 prints with integration in the backward direction.

Table III shows three sample parameter tapes illustrating many of the above features. Each of the three parameter tapes in the figure will accomplish exactly the same set of 4 runs; the optional character of many features of the para-

Table III: Three Sets of Parameters (all accomplishing identical runs) Illustrating Several Format Possibilities.

Example A:

```

00 991K
00 F 00 0320 0000 0000 J
00 993K
00 F 00 0001 4000 0000 J
00 F 00 F
00 48F 00 F
00 997K
80 F 00 48F
26 977N
6 3 7 -064 12K
6 33 7 -054 12F
6 31 7 01 9 033 4F
6 31 7 01 4F

```

Example B:

```

00 994K
00 F 00 F
00 48F 00 F
00 997K
80 F 00 48F
26 909N
991 032 993 00014 1F
6 3 7 -064 12K
6 33 7 -054 12F
6 31 7 01 9 033 4F
6 31 7 01 4F

```

Example C:

```

00 994K
00 F 00 F
00 48F 00 F
00 997K
80 F 00 48F
00 12K
00 F 00 F
00 48F 00 F
00 15K
80 F 00 48F
26 909N
991 032 993 00014
9 032 11 00014
6 3 7 -064 12K
6 33 7 -054 12F
6 31 7 01 9 033 4F
6 31 7 01 4F

```

meter format is illustrated. The assumed runs hypothesized in making up Table III require changing of integer type parameters; all three examples hence begin with DOI format and must be initially loaded with the white switch. (It is good practice to assist the operator by writing "white switch" on the parameter tape at this point.) Examples A and B have a distinct advantage over example C in that each comes immediately to a black switch stop after setting those parameters applicable to all runs - Example A would stop with reader having just read the 26 977N, Example B would stop with the reader having just read the 1F. If this first portion of the tape is marked "master parameters", the operator can be instructed in the event of sum check failure to reload "master parameters", then skip down tape to first uncompleted run and continue (see Appendix A for detailed sample instructions). If parameters are as in Example C such a restart could not be made without completely repeating the first run, since with parameters as in this example no stop will occur until the end of the first run. The Example C arrangement would of course be desirable for a single run since only one operator function is required to load all parameters and start the run. For any of the examples shown the computer will stop (if the black switch is not on ignore) after each of the four runs i.e. with the reader positioned successively at the end of each of the last four lines of the examples in Table III. At each of these stops a black switch restart must be given to continue with the next run. (Again, it is good practice to assist the operator by inserting a length of delays in the tape at these points and writing "black switch" directly on the tape.)

VI. OUTPUT FORMAT

A series of results of actual orbit code runs is presented in Table IV. The various samples have been selected to illustrate the normal features of the orbit code output format.

Results from five different runs are shown in the figure. A horizontal line has been drawn into the figure between each of the runs as an aid in explanation. Referring to the figure, each of the runs is seen to begin with a special line, which gives descriptive information, followed by a skipped line and then followed by successive similar lines in more or less regular format.

The initial descriptive line in each run consists of (1) a three digit base 16 number giving the number of R-K steps between prints, (2) a decimal fraction giving the value of the rest mass of the accelerated particle, (3) a decimal fraction giving the quantity $2^{-12}/\Delta r$, Δr being in cyclotron units and (4) a base 16 number giving the value of the sum check cell - since the setting of the sum check cell varies with different fields and different code configurations, this latter quantity serves as an identification of both the field and the features of the code employed, all-be-it a rather disguised identification. If the initial base 16 number in the descriptive line is preceded by four x's as in the second and third runs in Table 4, the integration is in the "backWard" direction.

Following the descriptive information successive lines of fractions are printed giving the values of the run variables at the beginning of the run and at successive azimuths thereafter, as specified by the "number of R-K steps between prints" parameter. The fourth run of the table has full run variable output, the successive fractions in a line being z , p_z , r , p_r , $\phi/4$, K , and $(1/64)\Sigma r$ all in

Table IV: Sample of Orbit Code Output

030 +93821323 +03016911 000000000

+25000000	+04000000	+00000000	+02800000	+00000000
+26270722	+03466910	+00638749	+02800000	+17754807
N1+L036-34				
+27197752	+02799159	+01352221	+02800000	+35541464
+27765054	+02009199	+02168838	+02800000	+53363193

XXXX030 +93821323 +03016911 N1+L036-34

+21500000	+02500000	+00000000	+03200000	+00000000
+21853356	+03043668	+02673477	+03200000	+19143110
+22305406	+03954380	+06199329	+03200000	+38386961
+23800861	+05636582	+12275570	+03200000	+57920228
+38113062	000000002J	0000000004		

XXXX030 +93821323 +03016911 N1+L036-34

+27765054	+02009199	+00000000	+02800000	
+27197779	+02799108	+00816824	+02800000	
LLLLLLLLLF				
+26270819	+03466812	+01530514	+02800000	
+25000211	+03999870	+02169487	+02800000	

030 +93821323 +03016911 N1+L036-36

+00400000	+00000000	+25000000	+02000000	+00000000	+02800000	+00000000
-00151302	-00131173	+25429324	+01453701	+00505935	+02800000	+17864553
-L470802-6						
-00351261	+00040919	+25645996	+00840116	+01033395	+02800000	+35743408
+00270764	+00114357	+25660313	+00196957	+01589046	+02800000	+53630399

010 +93821323 +03016911 80L60-6JFN

+04000000	+00000000	+32000000	-03500000	+00000000	+02800000
-00220820	-02868051	+16275272	-01547451	-00380515	+02813864
LLLLLLLLLF					
-04538485	-02163811	+25731440	+07805494	-10210726	+02813864
-03941405	+05641545	+32058694	-03998785	+03751615	+02827173
+07804444	+06966362	+14049880	-00841750	+02558834	+02840552
/+15189032//000000007 0000000005					

((((((((+25000000 000000007 0000000005

the same units as input. It will be noticed in this example that following lines are double spaced from the first. This results since the line of output is exactly the maximum length allowed by the printer and so a carriage return is fed in by the printer in addition to the one on the tape. To prevent this double spacing in the output, the quantity $(1/64)\Sigma r$ is often suppressed as described in Appendix H, in which case the format shown in the fifth run of the table is obtained. For median plane runs the output arrangement is the same, except that the columns for z , and p_z are not printed so the first column is now r , the second p_r , etc. Examples 1 and 2 are normal median plane runs while Example 3 is a median plane run with $(1/64)\Sigma r$ suppressed.

In all examples except the second, a short line consisting of a base 16 number is seen to occur between the second and third normal lines of output. This short word, as mentioned previously, indicates a sum check failure and is a 10 character base 16 number showing the negative absolute value of the amount by which the memory sum check fails to be zero. Due to particular characteristics of the printer the first character of this word usually prints during the return stroke of the printer thereby making reading difficult - the sum check failure in the first example is for instance "N1+L036-S4" but the "N" which is printed on top of the first "3" is quite difficult to discern. A sum check failure as in the first example in the figure will, as also mentioned previously, always occur whenever a new code and field are being assembled. The sum failure in the 3rd example reflects modification of the code to suppress the $(1/64)\Sigma r$, the failure in the 4th example reflects the modification to include axial motion and that in the final example again reflects suppression of the $(1/64)\Sigma r$. After each of the sum check failures in this sequence of runs the code has been restarted with the white switch which sets the sum cell to its proper

value so that the failure will not occur again. This is acceptable in this circumstance since each of the failures occurred due to changes deliberately made in the program. If such a failure had occurred other than after the second line of a given run or when no code changes had been made, a computer memory failure would be indicated and proper procedure would be to restart the series of runs beginning with a complete reloading of all tapes. (See sample instructions to operator, Appendix A).

The second of the group of runs shown in the table is seen to consist of four lines of normal output followed by a special fifth line. This special fifth line is printed whenever r exceeds its allowable limits, either maximum or minimum, and terminates the run. The first quantity in this line is a fraction giving the value of r at the point at which the r interval test failed, the second quantity is a base 16 number telling the number of R-K steps from the last print to the angle at which the r interval tests failed, and the final number is a similar base 16 number, giving the total number of prints performed up to the point where the r interval test failed.

As mentioned in section II, the variable z is required to be at all times less than $1/8$ in magnitude. If this test fails the run is also terminated and a line of output as shown at the end of example 5 is printed. This line is identical to that indicating r interval failure except that a "/" precedes the information (actually a double slant - "//" - is printed but, again due to characteristics of the printer, the first slant prints during the return pass of the printer and so is difficult to discern). The numerical quantities printed following the "/" are identical with the r interval failure format described in the previous paragraph.

In all of the examples except the fifth the kinetic

energy is seen to remain constant indicating that acceleration has not been included. In Example 5 the energy changes except between the second and third lines of output indicating that in the other three intervals accelerating gaps have been crossed.

The final line in Table IV, not attached to any of the examples, shows the output line which is obtained when the computer is restarted as described in Appendix K following one of the various white switch stops (other than the sum check stop already discussed). Output in this case consists of a series of parenthesis "((((((((" followed by a line of information again identical to that described in the r interval test failure above.

In addition to format features already mentioned, the third run in the table, it will be noticed, is a backward run starting with initial conditions which are identical to the final conditions from the first run of the table. It is seen that the backward run reproduces the results of the forward run to an accuracy of approximately 1 in 10^5 ; the magnitude of the disagreement reflects truncation errors in the integration process and is one of the ways available for estimating the effect of such errors. (A second and better way of estimating such errors is to make runs with a greater number of R-K steps per sector using the techniques described in either Appendix C or Appendix D).

VII. Computation of Running Time

Running time for the Orbit Code involves three principle factors: (1) the time required to carry out the basic integration step, (2) the time required to compute the magnetic field, and (3) the time required for printing out results. In addition to these three factors there is also a highly variable interval of time required for the loading of the program and field. (The variability in loading arises principally from tape handling time when fields and programs are loaded in DOI format. If a hex tape with fields and program is available loading time is fast and relatively uniform.)

In the following list times are given for each of the above segments of the computation. The time required for computation of the magnetic field is of course approximately proportional to the number of harmonics employed and so examples are given with several harmonic numbers in the field.

A. Median Plane Runs

1. Basic integration process-----0.32 sec/R-K step
2. Field computation
 - A. One harmonic-----0.09 sec/R-K step
 - B. Three harmonics-----0.27 sec/R-K step
 - C. Three harmonics plus one bump
harmonic-----0.36 sec/R-K step
3. Print time (median plane 5 col. print)---1.10 sec/line

B. Axial Motion Runs

1. Basic Integration Process-----0.54 sec/R-K step
2. Field Computation
 - A. One harmonic-----0.15 sec/R-K step
 - B. Three harmonics-----0.45 sec/R-K step
3. Print time (7 col. print)-----1.55 sec/line

C. Tape Loading Time (hexadecimal program and field tape)

1. 150 field values-----27 sec.
2. 450 field values-----38 sec.

Section VIII. Flow Charts, Temporary Storage Guides, and Order Pairs for the Program

In order to facilitate possible revisions of the code, it is written in blocks using relative addresses within blocks and with an S box¹ assigned to each block so that inter-block transfers can also be relative using S addresses. As mentioned previously the program is also written in two parts, the first being the "Load B routine" which places the field in memory in the proper arrangement, and the second, which overwrites the Load B routine, consisting of the main program and the parameter loading routines. In the following pages the Load B routine is covered first in three pages, the first page showing the arrangement of the Load B program tape including the S box settings, and the second and third sheets giving the order pairs for the successive major blocks of the Load B routine.

Following the Load B routine similar information is given for the main program including at the beginning a functional flow chart for the routine. In the flow chart solid lines denote functional blocks whereas the dotted lines denote coding blocks. In a number of cases it will be noted that coding blocks include several functional blocks.

Notice in the flow charts that entry in the main loop of the program at the beginning of a run is at the point immediately following the gap crossing test and the gap crossing test is hence first made after completion of the first Runge-Kutta step. An accelerating gap placed at $\theta=0$ will therefore not be crossed until the end of the first full revolutions and the initial energy employed in such a run should thus be the value after the initial crossing of the $\theta=0$ gap. Note also in the flow charts that the run termination exit from the main loop occurs immediately after

the last printing of the output; if this printing occurs at the same azimuth as a gap crossing the print will give the after gap crossing energy.

Following the main flow chart, temporary storage guides are given showing the usage of the S3 and S5 temporary storage. S4 locations are also used for temporary storage but with the restriction that nothing of a semipermanent nature can be stored here, i.e. at the end of a block all information in S4 is assumed to be no longer needed and can be overwritten by the next block. Since S4 is used for innumerable purposes no storage breakdown is given for this section. If, in the running of the orbit code, a stop of unexplained character occurs it is usually useful to obtain order pair and fraction post mortems of the S3 and S5 temporary storage locations. From this data a great deal of information can be discerned concerning the particular orbit.

Following the temporary storage guides, pages of order pair lists for the various coding blocks are included and in addition, for some blocks, a detailed flow chart of the block is given.

The program is believed to be completely internally protected against undetected overflow. It will be noted in several places that this protection is often at the expense of operational speed. (Divide orders are used rather than left shifts, etc.) In view of the frequent important decisions based on results from this code, this protection is felt to be a wise precaution.

PROGRAM TAPE I - "LOAD B PROGRAM"

Abs. Addr.	Rel. Addr.	Order Pairs	Comments
999			Library Decimal Order
.			Input Routine
.			
.			
1023			

S Box Settings

3		00	F	00	4F	Zero'th location black	S3
4		00	F	00	25F	"	S4
5		00	F	00	33F	"	S5
6		00	F	00	289F	"	S6
7		00	F	00	129F	"	S7
8		00	F	00	371F	"	S8
9		00	F	00	55F	"	S9
10		00	F	00	410F	"	SK
11		00	F	00	435F	"	SS
12		00	F	00	64F	"	SN
13		00	F	00	112F	"	SJ
14		00	F	00	330F	"	SF
15		00	F	00	227F	"	SL

Coding Section S9

New Field Loader Routine

55	0	L5	36L	40	17L
56	1	L5	15L	42	3S4
57	2	F1	15S3	L0	15S3
58	3	40	S4	L0	16S3
59	4	L0	16S3	40	1S4

Abs. Addr.	Rel. Addr.	Order Pairs				Comments
60	5	40	6S4	19	18F	
61	6	L4	17S3	10	18F	
62	7	42	10L	42	27L	
63	8	F1	19S3	40	2S4	
64	9	F5	2S4	40	2S4	
65	10	32	11L	80	...F	
66	11	26	9L	41	4S4	
67	12	L5	3S4	42	19L	
68	13	L5	17S3	46	14L	
69	14	50	...F	50	14L	
70	15	26	S7	SL	SS	
71	16	36	17L	0F	1F	
72	17	S5	F	22	19L	
73	18	L5	38L	74	2S5	} Multiply H's and G's by I soch. code scale factor
74	19	00	2F	40	...F	
75	20	L5	19L	L0	6S4	
76	21	42	19L	F5	4S4	
77	22	40	4S4	L0	14S3	
78	23	36	24L	22	14L	
79	24	F1	18S3	L4	14S3	
80	25	L4	19S3	40	5S4	
81	26	F5	5S4	40	5S4	
82	27	32	28L	80	...F	
83	28	26	26L	L5	37L	
84	29	40	17L	F5	3S4	
85	30	42	3S4	F5	S4	
86	31	40	S4	L3	S4	
87	32	36	33L	22	33L	
88	33	20	33L	F5	1S4	
89	34	40	1S4	32	35L	

Abs. Addr.	Rel. Addr.	Order Pairs	Comments
90	35	26 8L 24 999F	
91	36	S5 F 22 19L	
92	37	N0 F N0 F	
93	38	20 F 00 F	

Coding Section 40S9

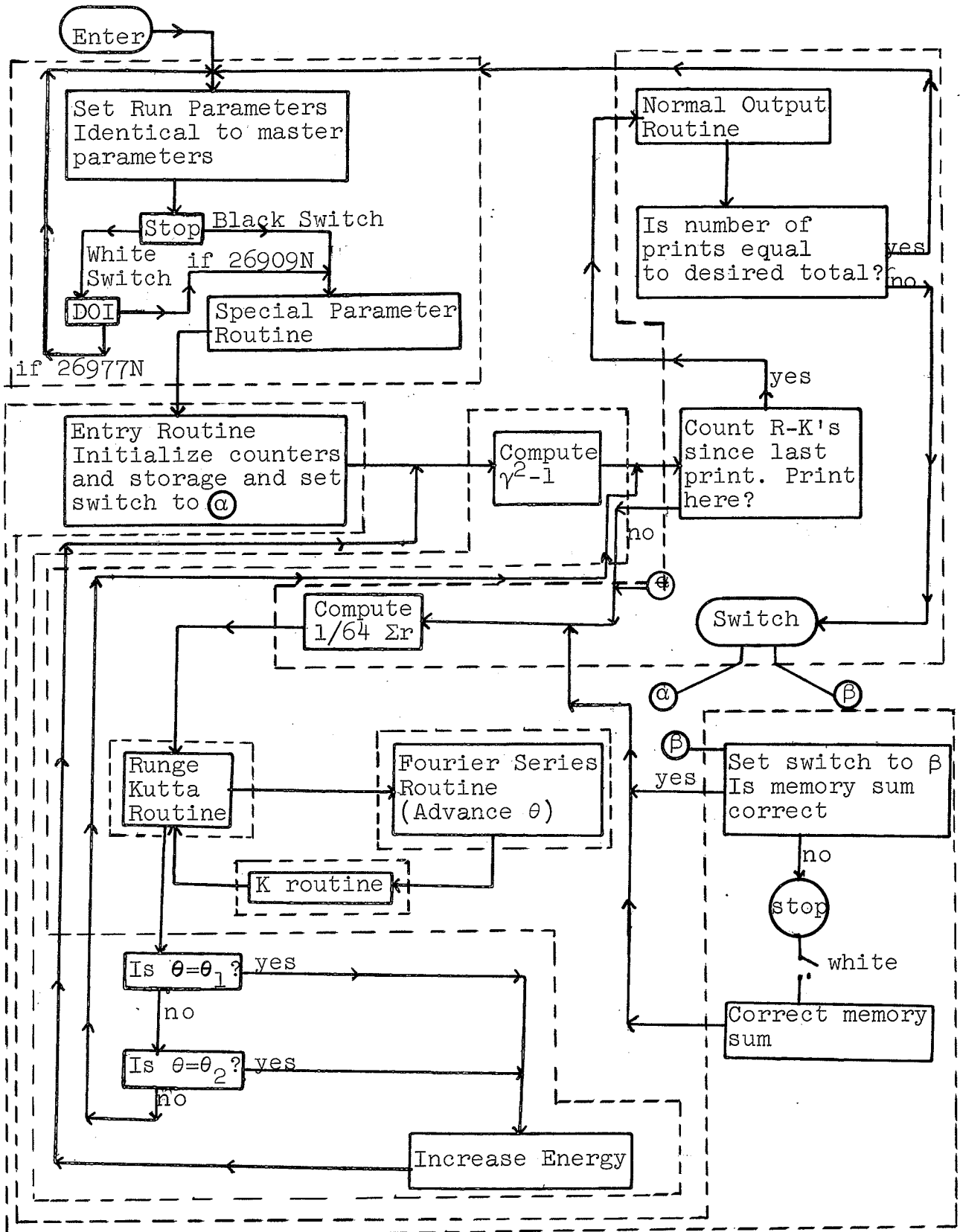
Compute E_0 and $2^{-12}/\Delta r$ Routine

95	0	50 6S5 7J 16L	⑦	.93114
96	1	50 5S5 70 17L	⑥	.00000511
97	2	S5 F 40 F		$m_0 c^2 \times 10^{-5}$
98	3	S5 F 40 (996)F		$(m_0 c^2 \times 10^n) > 1/10$
99	4	75 18L 40 1F		00 F 00 10F
100	5	L3 1F 36 3L		
101	6	50 3S5 75 5S5	④ ⑥	
102	7	7J 1S5 40 1F	②	
103	8	50 1F 7J S5	①	
104	9	40 1F 50 F		
105	10	7J 2S5 40 F	③	
106	11	50 F 7J 4S5	⑤	
107	12	40 F 50 F		
108	13	75 19L 66 1F		.1282474
109	14	S5 F 40 (17)F		
110	15	26 55F 00 F		
111	16	40 F 00 4311 4000 0000J		
112	17	00 F 00 0000 0511 0000J		
113	18	00 F 00 10F		
114	19	00 F 00 1282 4740 0000J		

24 999N

Transfer directive

Main Program Flow Chart



MAIN PROGRAM ORGANIZATION

Memory layout, main routine:

003 - 015: S box parameters
 004 - 024: S3
 (004 - 015) Run Parameters
 (016 - 024) Field Parameters
 025 - 032: S4 Temporary Storage
 033 - 054: S5 " "
 055 - 063: S9 routine - Library R-1
 064 - 111: SN, Interpolate Routine
 112 - 128: SJ, Cosine Routine
 129 - 226: S7, Fourier Series Routine
 227 - 290: SL, Gap Cross and Punch Routine
 289 - 329: S6, Runge-Kutta Routine
 330 - 371: SF, "K" Routine
 371 - 408: S8, Constants and Sum Check and Entry Routines
 410 - 434: SK, Cosine Table
 435 - 908: SS, B, H, G, h, g Table
 909 - 998: New Parameter Routine
 999 - 1023: Library Decimal Order Input Routine

Temporary Storage Guides

Coding Section S3

Parameters

Abs. Addr.	Rel. Addr.	Parameter	Significance
4	0	z	Described in Table II
5	1	p_z	" " " "
6	2	r	" " " "
7	3	p_r	" " " "
8	4	$\phi/4$	" " " "

Abs. Addr.	Rel. Addr.	Parameter	Significance
9	5	K	Described in Table II
10	6	$1/64 \Sigma r$	" " " "
11	7	δK	" " " "
12	8	$\theta_1 \times 2^{-18}$	" " " "
13	9	$\theta_2 \times 2^{-18}$	" " " "
14	10	E_0	" " " "
15	11	$-1 + (R_p \times 2^{-39})$	" " " "
16	12	$-1 + (R_R \times 2^{-39})$	" " " "
17	13	$2^{-12}/\Delta r$	Calculated by Load B Program
18	14	$a \times 2^{-39}$	Described on Page 11
19	15	$H \times 2^{-39}$	" " " "
20	16	$h \times 2^{-39}$	" " " "
21	17	$d \times 2^{-19}$	" " " "
22	18	$b \times 2^{-39}$	" " " "
23	19	$\alpha \times 2^{-39}$	" " " "
24	20	$\beta \times 2^{-39}$	" " " "

Coding Section S5

Temporary Storage

033	0	q_0	} Runge Kutta Round-off Corrections
034	1	q_1	
035	2	q_2	
036	3	q_3	
037	4	q_4	
038	5	θ	$\theta \times 2^{19}$ = angle in units of R-K steps
039	6	θ_c	switch to signal θ advance on alternate Fourier Series cycles
040	7	Count R_p	count R-K's between prints
041	8	Count R_R	" prints per run
042	9	$\gamma^2 - 1$	momentum squared

Abs. Addr.	Rel. Addr.	Parameter	Significance
043	10	$B(r_i)$	magnetic field at grid points
044	11	$B(r_i + 1, \theta)$	
045	12	$B(r_i + 2, \theta)$	
046	13	$B(r_i + 3, \theta)$	θ derivative of field at grid points
047	14	$B_\theta(r_i, \theta)$	
048	15	$B_\theta(r_i + 1, \theta)$	
049	16	$B_\theta(r_i + 2, \theta)$	fractional part of $r/\Delta r$
050	17	$B_\theta(r_i + 3, \theta)$	
051	18	X	
052	19	$B(r, \theta)$	field at r, θ .
053	20	$B_r(r)$	r derivative of field at r, θ .
054	21	$B_\theta(r)$	θ " " " " " "

PROGRAM TAPE II - "MAIN PROGRAM"

Coding Block S9

Square Root Routine (Library Routine R-1)

55	0	40	1F	K5	F	hang. if square root of negative number
56	1	42	8L	51	1F	
57	2	10	1F	SJ	F	
58	3	40	2F	50	F	
59	4	L5	1F	66	2F	
60	5	S5	F	L0	2F	
61	6	10	1F	36	8L	
62	7	L4	2F	26	3L	
63	8	L5	2F	22	...F	

Coding Section SN
Interpolation Subroutine

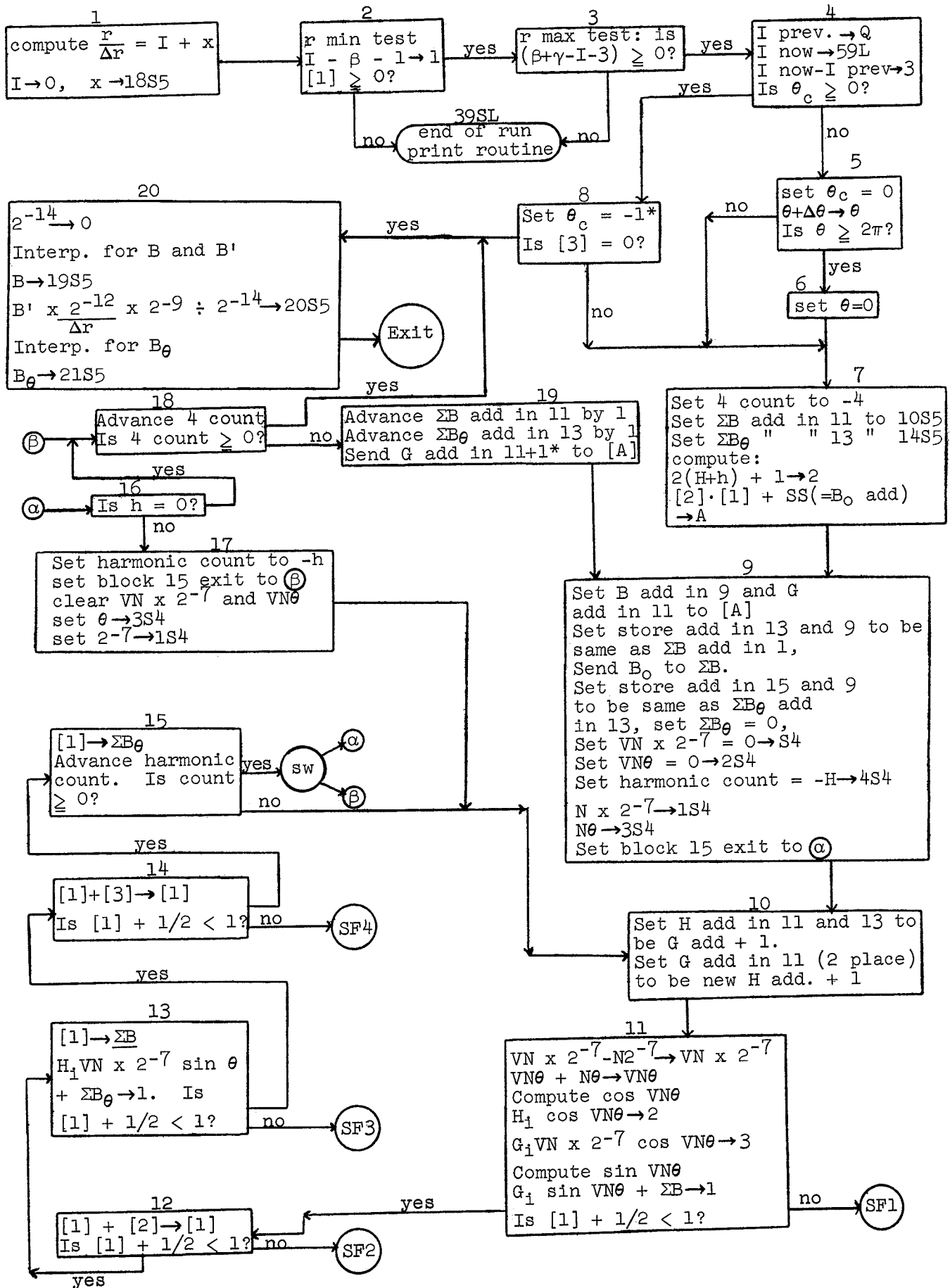
Abs. Addr.	Rel. Addr.	Order Pairs				Comments
064	0	40	S4	K5	F	
065	1	40	1S4	10	20F	
066	2	42	22L	42	39L	
067	3	F5	22L	42	19L	
068	4	42	35L	F5	19L	
069	5	42	17L	42	36L	
070	6	F5	17L	42	24L	
071	7	42	38L	09	1F	
072	8	L4	S4	40	2S4	
073	9	10	1F	40	3S4	
074	10	49	4S4	L5	S4	
075	11	10	1F	40	5S4	
076	12	L4	4S4	40	6S4	
077	13	L5	3S4	L0	4S4	
078	14	50	S4	40	4S4	
079	15	7J	2S4	40	S4	
080	16	50	S4	7J	47L	
081	17	40	S4	50	...F	
082	18	79	5S4	50	3S4	
083	19	40	3S4	7J	...F	
084	20	L4	3S4	40	3S4	
085	21	50	6S4	7J	4S4	
086	22	40	5S4	50	...F	
087	23	7J	4S4	10	1F	
088	24	40	4S4	50	...F	

Abs. Addr.	Rel. Addr.	Order Pairs				Comments
089	25	7J	6S4	10	1F	
090	26	L0	4S4	40	6S4	
091	27	50	3S4	7J	5S4	
092	28	00	2F	40	4S4	
093	29	50	6S4	7J	S4	
094	30	L4	4S4	40	4S4	
095	31	L5	1S4	42	46L	
096	32	36	46L	LJ	2S4	
097	33	50	6S4	40	6S4	
098	34	7J	47L	L4	3S4	
099	35	40	1S4	L5	...F	
100	36	50	1S4	L0	...F	
101	37	40	3S4	7J	6S4	
102	38	40	2S4	L5	...F	
103	39	50	3S4	L0	...F	
104	40	40	1S4	7J	5S4	
105	41	40	5S4	50	1S4	
106	42	7J	S4	10	3F	
107	43	L4	2S4	L4	5S4	
108	44	40	2S4	49	S4	
109	45	L5	2S4	66	S4	
110	46	L5	4S4	22	...F	
111	47	40	F	00	1666 6666 6667J	

Coding Section SJ
Cosine Routine

112	0	40	14L	K5	F
113	1	42	15L	42	16L
114	2	L5	14L	L0	1S8
115	3	32	2L	40	14L
116	4	L4	1S8	40	F

Fourier Series Routine (S7)
Flow Chart



Abs. Addr.	Rel. Addr.	Order Pairs					Comments
117	5	L4	14L	10	1F		
118	6	40	1F	36	8L		
119	7	L5	F	22	8L		
120	8	L1	14L	40	F		
121	9	80	2F	L0	1S8		
122	10	32	12L	L5	15L		
123	11	L4	F	40	14L		
124	12	26	14L	L5	16L		
125	13	L6	1F	40	14L		
126	14	00	F	00	F		
127	15	L5	SK	22	... F		
128	16	L1	SK	22	... F		

Coding Section S7
Fourier Series Routine

129	0	L5	S4	L0	1S4	} 11		
130	1	40	S4	L5	2S4			
131	2	L4	3S4	40	2S4			
132	3	<u>50</u>	F	50	3L			
133	4	26	SJ	40	F			to cos routine
134	5	50	F	7J	...F			H
135	6	40	2F	50	F			
136	7	7J	S4	40	F			
137	8	50	F	(7J)	...F			G
138	9	40	3F	L5	2S4			
139	10	L4	4S8	50	10L			
140	11	26	SJ	40	F			
141	12	50	F	(79)	...F		G	
142	13	<u>50</u>	41L	L4	...F		Σ B left add used in 36L	
143	14	40	1F	LL	1F			

Abs. Addr.	Rel. Addr.	Order Pairs					Comments
144	15	36	16L	SF	1F	11	stop if $ B-G \sin \theta $
145	16	L5	1F	L4	2F		
146	17	40	1F	LL	1F	12	stop if $ B-G \sin \theta +$
147	18	36	19L	SF	2F		
148	19	L5	1F	40	...F	13	H
149	20	50	F	7J	S4		
150	21	40	F	50	...F	13	ΣB_θ
151	22	7J	F	L4	...F		
152	23	40	1F	LL	1F	14	stop if $ B_\theta + NH \sin $
153	24	36	25L	SF	3F		
154	25	L5	1F	L4	3F	14	stop if $ B_\theta + NH \sin$
155	26	40	1F	LL	1F		
156	27	36	28L	SF	4F	15	ΣB_θ
157	28	L5	1F	40	...F		
158	29	F5	4S4	40	4S4	15	number of sectors (N from eq. 6)
159	30	36	...F	F5	8L		
160	31	42	5L	42	21L	10	
161	32	F5	5L	42	8L		
162	33	42	12L	26	L	17	Set by entry interlude if used (=6 in prog. tape)
163	34	00	F	00	3F		
164	35	L3	16S3	36	41L	16	
165	36	40	4S4	L5	13L		
166	37	46	30L	41	S4	17	
167	38	40	2S4	L5	5S5		
168	39	40	3S4	19	(6)F	18	
169	40	40	1S4	22	30L		
170	41	F5	5S4	40	5S4	18	
171	42	32	88L	F5	13L		
172	43	42	13L	F5	22L	19	
173	44	42	22L	F5	8L		

Abs. Addr.	Rel. Addr.	Order Pairs				Comments	
174	45	42	8L	42	47L	B_0 ΣB left add. used in 57L ΣB_0	
175	46	L5	13L	42	19L		
176	47	42	48L	L5	...F		
177	48	<u>50</u>	35L	40	...F		
178	49	L5	22L	42	50L		
179	50	42	28L	41	...F		
180	51	40	S4	40	2S4		
181	52	L1	15S3	40	4S4		
182	53	50	9S8	L5	34L		
183	54	00	(32)F	40	1S4		Set by entry interlude if used (=32 in prog. tape)
184	55	50	5S5	75	34L		
185	56	00	39F	40	3S4		
186	57	L5	48L	46	30L		
187	58	22	30L	00	S5		
188	59	00	F	00	F	δ	
189	60	50	2S3	75	13S3	1	
190	61	10	27F	40	F		
191	62	L5	F	F0	20S3		
192	63	40	1F	32	64L	2	
193	64	26	39SL	L5	20S3		
194	65	F4	14S3	L0	8S8		
195	66	L0	F	32	67L	3	if $r > r_{\max.} - \Delta r$
196	67	26	39SL	S5	SS	1	rt. add. used in 83L
197	68	40	18S5	50	59L		
198	69	L5	F	40	59L	4	
199	70	S0	F	40	3F		
200	71	L5	6S5	36	84L		
201	72	41	6S5	L5	5S5		
202	73	L4	5S8	40	5S5	5	
203	74	L0	1S8	32	75L		

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
204	75	26	76L 41 5S5	6
205	76	L1	8S8 40 5S4	
206	77	L5	6S8 42 13L	
207	78	L5	7S8 42 22L	
208	79	L5	15S3 L4 16S3	
209	80	80	1F F4 9S8	
210	81	40	2F 50 2F	7
211	82	75	1F S5 F	
212	83	L4	67L 26 45L	
213	84	F1	6S5 40 6S5	
214	85	L3	3F 32 88L	
215	86	26	76L 00 F	
216	87	00	F 00 F	
217	88	00	F 19 13F	
218	89	40	F L5 18S5	8
219	90	<u>J0</u>	<u>10S5</u> 50 90L	
220	91	26	SN 40 19S5	
221	92	75	13S3 10 (9)F	
222	93	66	F S5 F	
223	94	40	20S5 L5 18S5	
224	95	<u>50</u>	14S5 50 95L	
225	96	26	SN 40 21S5	
226	97	26	SF 26 30S8	
				Set by entry interlude if used(set = 9 in prog. tape).
				exit

Coding Section SL

New Gap Crossing and Punch Routine

227	0	L5	5S5	L0	8S3
228	1	40	F	L3	F
229	2	32	5L	L5	5S5
230	3	L0	9S3	40	F
231	4	L3	F	32	5L

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
232	5	26	22L 50 4S3	to punch routine
233	6	7J	4S3 40 F	
234	7	50	F 7J F	
235	8	40	1F 50 1F	
236	9	7J	3S8 40 1F	
237	10	LJ	1F L0 F	
238	11	40	F 19 2F	
239	12	40	1F 50 F	
240	13	7J	F L0 1F	
241	14	00	2F 40 F	
242	15	50	F 7J 7S3	
243	16	L4	5S3 40 5S3	
244	17	L5	5S3 66 10S3	compute $\gamma^2 - 1$
245	18	S5	F 40 1F	
246	19	00	1F 40 F	
247	20	10	1F 7J 1F	
248	21	L4	F 40 9S5	
249	22	L5	34L 42 25L	punch routine
250	23	F5	7S5 40 7S5	
251	24	L0	11S3 32 35L	
252	25	92	515F L5 ...F	
253	26	50	8F 50 26L	
254	27	26	46L F5 25L	
255	28	42	25L L0 38L	
256	29	32	25L 92 131F	
257	30	F5	8S5 40 8S5	
258	31	L0	12S3 36 ...F	set by entry routine
259	32	92	143F 27 977F	
260	33	L5	33L 50 10S8	reset 31L
261	34	42	31L 50 S3	1st word to punch

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
262	35	41	7S5 L5 2S3	} last word to punch r and z interval failure punch routine
263	36	10	6F L4 6S3	
264	37	40	6S3 22 21S6	
265	38	12	515F L5 7S3	
266	39	92	515F L5 2S3	
267	40	50	8F 50 40L	
268	41	26	46L L5 7S5	
269	42	82	40F 92 967F	
270	43	L5	8S5 82 40F	
271	44	92	137F L5 37S6	
272	45	42	21S6 26 977F	

Coding Section 46SL

Convert to decimal and punch routine

273	0	40	F L1 16L	Library Routine P-2
274	1	S4	L 46 1L	
275	2	42	14L 36 6L	
276	3	L5	F 36 5L	
277	4	92	706F 22 5L	
278	5	92	642F 00 2F	
279	6	J0	8L 7J 17L	
280	7	42	8L 22 8L	
281	8	00	63F 19 F	
282	9	L6	F 10 39F	
283	10	75	15L 00 36F	
284	11	82	4F 10 40F	
285	12	L5	1L L0 16L	
286	13	46	1L 36 10L	
287	14	92	965F 22 F	
288	15	00	F 00 10F	
289	16	S4	1F 00 1023F	
290	17	00	1F K9 1000F	

Coding Section S6
R-K Routine

Library routine F-1 with following changes:

- (1) 0, 1 and 2 relative not used. These cells are over-written by P-2 routine which preceds F-1 in memory.
- (2) Scaling parameter m in 8L and 11L is written into routine rather than being used as a program parameter.
- (3) Exit order is permanently set to exit to gap crossing routine. No subroutine type of entry is used.
- (4) Enter routine at right of 21L.
- (5) Exit to auxiliary subroutine permanently set.

Abs. Addr.	Rel. Addr.	Order Pairs	Comments
291	2	00	F 00
292	3	L5	($q_{i,j}$) F 40
293	4	L5	($k_{i,j}$) F 40
294	5	L0	(1) F L0
295	6	40	3F 50 (A_j)F
296	7	7J	3F L4
297	8	10	(m)F 40
298	9	L4	(y_{ij})F 40 ($y_{i,j+1}$)F
299	10	L5	3F 50
300	11	00	(m)F 40
301	12	50	(C_j)F 7J
302	13	L0	F L4
303	14	L4	3F L4
304	15	L4	3F 40 ($q_{i,j+1}$)F
305	16	L5	9L L4
306	17	42	9L 46
307	18	L4	39L 46
308	19	L4	40L 42
309	20	46	3L L0
310	21	36	3L L5 (33)L

From 21
 By 20
 By 18
 By 23
 By 24
 } Step y_i
 Form $r_{i,j+1}$
 }
 } increase all
 addresses
 depending on
 i by 1 until
 i=n
 By 25
 By 19
 By 22

Abs. Addr.	Rel. Addr.	Order Pairs				Comments
311	22	42	21L 36	SL	From 2' By 2	Increase j from 0 to 3 and then exit
312	23	46	5L 10	10F	}	Adjust addresses which depend on j Call in auxiliary sub-routine Clear 2F so that it can be used as zero Start new i cycle
313	24	L4	18L 42	6L		
314	25	46	12L 50	25L		
315	26	26	60S7 41	2F		
316	27	L5	38L 26	17L		
317	28	40	F 00	F	1/2	C_0, C_3
318	29	NO	F 00	F	-1/2	A_0
319	30	40	F 00	2071 0678 1186	J	$1/\sqrt{2} C_1, A_2$
320	31	80	F 00	2928 9321 8814	J	$-1/\sqrt{2} A_1, C_2$
321	32	80	F 00	1666 6666 6667	J	$-5/6 A_3$
322	33	LJ 1025F	06 1058L		-11, 1 25, 34L	} Expressed in units of 2-9, 2-19, 2-29, 2-39 Addresses used to set addresses to refer to the constants A, C, j and make the address in 5L, 1 or 2 according as $B, 2$ or 1, and to stop the address in 21, dependent on j, and to stop when positive. "4" replaced by "6" when median plane overwrite is used.
323	34	LJ 3074F	06 3107L		-9 2, 27 35L	
324	35	LF 2F	06 2084L		-8, 2 26, 36L	
325	36	LJ 1025F	07 37L		-11, 1 28, 37L	
326	37	64	38F 00	33L		
327	38	80	4F 00	4F		
328	39	00	21F 00	21F		
329	40	00	8F 00	8F		

Coding Section SF

"K" Routine

Abs. Addr.	Rel. Addr.	Order Pairs				Comments
330	0	50	3S3	79	3S3	Note: $\tau = \frac{d}{d\theta}$
331	1	40	F	50	1S3	
332	2	79	1S3	L4	1F	
333	3	L4	9S5	50	3L	
334	4	26	S9	40	3S4	
335	5	50	2S3	(75)	3S3	
336	6	66	3S4	S5	F	← hang. if $ r' (= \frac{r_{pr}}{q}) \geq 1$
337	7	40	5S4	7J	2S8	
338	8	40	2S4	50	2S3	
339	9	(75)	1S3	66	3S4	÷ hang. if $ z' (= \frac{r_{pz}}{q}) \geq 1$
340	10	S5	F	40	6S4	
341	11	7J	2S8	40	S4	
342	12	19	(8)F	40	7S4	scaling on dB set by entry interlude if used (set = 8 in program tape).
343	13	L5	5S3	66	10S3	←
344	14	7J	2S3	L4	2S3	÷ hang. if $K > E_0$
345	15	L0	3S4	10	2F	
346	16	66	3S4	7J	2S8	÷ hang. if $ \phi'/4 \geq 1$
347	17	40	4S4	50	5S4	
348	18	7J	21S5	40	5S4	
349	19	50	2S3	7J	2S3	
350	20	40	F	50	F	
351	21	7J	20S5	L0	5S4	
352	22	40	F	L5	S3	
353	23	66	2S3	S5	F	÷ hang. if $ z \geq r$
354	24	40	5S4	(71)	F	
355	25	66	7S4	79	2S8	÷ hang. if $ P'z \geq 1$
356	26	40	1S4	19	1F	
357	27	40	F	50	2S3	
358	28	7J	19S5	40	1F	
359	29	50	5S4	7J	6S4	

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
360	30	40	2F 50 2F	
361	31	75	21S5 10 2F	
362	32	66	7S4 S5 F	hang. if $\left \frac{ZP_z}{4q} B\theta \right \geq 0$
363	33	40	2F L1 3S4	
364	34	10	2F L0 2F	
365	35	L4	1F 66 F	hang. if $ P'r \geq 1$
366	36	(79)	2S8 40 3S4	
367	37	LL	2S3 32 38L	
378	38	KK	1F L5 S3	stop if $ r \geq 1/2$
369	39	00	2F 40 F	
370	40	LL	F 32 26S6	
371	41	92	455F 26 39SL	test is $ Z \geq 1/8$ end run if yes

Coding Section S8

Constants

371	0			
372	1		"2 π " = 2 times no. of R-K steps/rev. x 2 ⁻¹⁹	
373	2		2 ^m $\Delta\theta_{rad.} = \pi/6$ in prog. tape. ⁶	
374	3		1/3	
375	4		"3 $\pi/2$ " = 3/2 times no. of R-K steps/rev. x 2 ⁻¹⁹	
376	5		2 ⁻¹⁹ = $\Delta\theta$	
377	6	00	F 00 10S5	Initial address used in S7
378	7	00	F 00 14S5	" " " "
379	8	4*		
380	9	0		

⁶m in 373 must agree with m in 297 and 300. $\Delta\theta_r$ is angular extent of R-K step in radians. See Appendix C. to change.

Cosing Section 10S8
New Sum Check and Entry Routine

Abs. Addr.	Rel. Addr.	Order Pairs				Comments
381	0	L5	15L	42	1L	
382	1	41	F	L5	...F	
383	2	L4	F	40	F	
384	3	F5	1L	42	1L	
385	4	L0	18L	32	1L	
386	5	L5	F	L0	5S7	
387	6	L0	8S7	L0	12S7	
388	7	L0	21S7	L0	47S7	
389	8	L0	14SJ	L0	59S7	
390	9	L4	20S3	L4	13S3	
391	10	L4	14S3	L4	15S3	
392	11	L4	16S3	L4	19S3	
393	12	L0	940F	L0	927F	
394	13	40	F	L3	F	
395	14	36	35SL	82	40F	
396	15	92	131F	4F	S9	
397	16	L5	19L	L0	F	
398	17	40	19L	26	L	
399	18	N1	F	L5	986F	
400	19	00	...F	00	...F	sum check cell
401	20	L5	58S7	42	21L	Entry Routine
402	21	40	59S7	41	...F	
403	22	F5	21L	42	21L	
404	23	L0	28L	32	21L	
405	24	L5	11S3	42	7S5	
406	25	L5	25L	50	33SL	
407	26	42	31SL	41	6S3	
408	27	92	135F	26	17SL	
409	28	N0	59S7	41	9S5	

Coding Block SS
Field Storage

Abs. Addr.	Rel. Addr.	Order Pairs	Comments
410	0	$B_0(\beta\Delta r)$	
411	1	$H_1(\beta\Delta r)$	
.	.	.	
.	.	.	
.	.	.	

Parameter Routine

909	0	L5	1L	42	18L
910	1	41	3F	50	30L
911	2	41	2F	81	4F
912	3	L0	22L	36	20L
913	4	L4	21L	40	F
914	5	L5	21L	22	9L
915	6	50	F	74	22L
916	7	00	39F	40	F
917	8	50	1F	75	22L
918	9	S5	F	40	1F
919	10	91	4F	36	23L
920	11	50	1F	L5	F
921	12	66	1F	10	1F
922	13	L5	F	L4	1F
923	14	40	F	SJ	F
924	15	40	1F	L1	2F
925	16	32	18L	L1	F
926	17	40	F	L1	1F
927	18	40	1F	26	...F
928	19	50	F	79	F

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
929	20	40	2F 22	2L
930	21	00	F 00	5F
931	22	00	F 00	10F
932	23	L0	22L 36	25L
933	24	L4	22L 26	6L
934	25	40	S4 L3	S4
935	26	36	28L L5	51L
936	27	42	18L 26	11L
937	28	L5	29L 42	18L
938	29	26	11L 00	35L
939	30	L5	3F 32	32L
940	31	L5	1F 40	...F
941	32	26	1L L5	F
942	33	42	31L F1	3F
943	34	40	3F 26	2L
944	35	L5	63L 40	12S7
945	36	L5	19L 40	8S7
946	37	L5	64L 40	5SF
947	38	L5	66L 40	36SF
948	39	L5	65L 40	9SF
949	40	L5	67L 40	24SF
950	41	92	911F 26	48L
951	42	L5	59L 40	12S7
952	43	L5	57L 40	8S7
953	44	L5	58L 40	9SF
954	45	L5	60L 40	5SF
955	46	L5	61L 40	36SF
956	47	L5	62L 40	24SF
957	48	L5	F 42	12S3
958	49	L5	11S3 00	28F

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
959	50	82	12F 92 967F	
960	51	L5	10S3 50 42L	
961	52	50	8F 50 52L	
962	53	26	46SL L5 13S3	
963	54	50	8F 50 54L	
964	55	26	46SL L5 29S8	
965	56	82	40F 26 30S8	entry routine
966	57	50	F 7J F	
967	58	75	1S3 66 3S4	
968	59	50	F 79 77L	
969	60	50	2S3 75 3S3	
970	61	79	2S8 40 3S4	
971	62	40	5S4 71 F	
972	63	50	F 7J F	
973	64	50	2S3 71 3S3	
974	65	71	1S3 66 3S4	
975	66	7J	2S8 40 3S4	
976	67	40	5S4 75 F	
977	68	L5	59L 42 70L	
978	69	L5	69L 50 S3	
979	70	42	71L L5 ...F	
980	71	50	F 40 ...F	
981	72	F5	71L 42 71L	
982	73	F5	70L 42 70L	
983	74	L0	76L 32 70L	
984	75	24	L 26 999F	
985	76	N2	71L L5 90L	
986	77	00	F 00 0000 1000 0000J	Z
987	78	00	F 00 F	P _Z
988	79	00	F 00 2500 0000 0000J	R

Abs. Addr.	Rel. Addr.	Order	Pairs	Comments
989	80	00	F 00 0850 0000 0000J	Pr
990	81	00	F 00 F	$\phi/4$
991	82	00	F 00 0280 0000 0000J	K
992	83	<u>00</u>	<u>F 00</u> <u>F</u>	Not used
993	84	00	F 00 0002 8000 0000J	ΔK
994	85	00	F 00 1F	gap 1
995	86	00	F 00 1F	gap 2
996	87	E_o (set by Load B routine)
997	88	80	F 00 16F	$R_k=16$
998	89	80	F 00 <u>F</u>	R_p is irrelevant
			26 977N	final directive
			End Main Program	

Median Plane Overwrite

331	26	333F	00	F	} Load this tape with white switch after main program tape to set code for median plane runs
338	40	27F	26	343F	
347	40	29F	22	356F	
359	22	363F	00	F	
364	10	2F	50	6F	
261	42	258F	50	6F	
135	40	2F	22	138F	
149	26	158F	00	F	
219	50	43F	50	219F	
221	26	330F	00	F	
327	80	6F	00	6F	
			26	977N	

Anti-Median Plane Overwrite

Abs. Addr.	Rel. Addr.	Order Pairs				Comments
331	40	F	50	5F	} Load this tape with white switch to make axial motion runs with a median plane program tape.	
338	40	27F	50	6F		
347	40	29F	50	30F		
359	50	30F	7J	31F		
364	10	2F	L0	2F		
261	42	258F	50	4F		
135	40	2F	50	F		
149	50	F	7J	25F		
219	J0	43F	50	219F		
221	75	17F	10	9F		
327	80	4F	00	4F		
265	12	515F	L5	10F		
			26	977N		

Appendix A: Sample Instructions for Operator

A standard instruction sheet is available for use in Mystic production runs; the following sample instructions are written in format corresponding to this standard sheet. As a precaution against operator error it is in general good policy to have no more than three tapes involved in production runs. Hence runs of the type shown in the first two samples should if possible be made with the preparer of the run present to assist the operator in selecting proper tapes.

1. Single median plane run using DOI input tapes.

Tape	Start	Stop	Comments
"Load B"	Bootstrap	24	Entire tape loads
B Parameters	Black Sw.	24	Entire tape loads
Main field	Black Sw.	20	Entire tape loads
Bump field	Black Sw.	24	Entire tape loads
Main Program	Black Sw.	24	80% of tape loads
	Black Sw.	24	remainder of tape loads
Med. Plane Overwrite	White Sw.	24	Entire tape loads
Run Parameter	xxx Sw.	4F	Memory sum check must be set after 2nd print.
	White Sw.	24	End of run

xxx = white if initial parameters are in DOI format.

= black if initial parameters are in special routine format.

For runs with axial motion included the procedure is the same as above except the Median Plane Overwrite step is omitted.

2. To make Hexadecimal Program Tape.

Make at least one run as in example 1 so as to set sum check cell. At end of this run without clearing memory:

Tape	Start	Stop	Comments
Rev. x-16S	Boot-no clear	24	Part of tape goes in
	white Sw.	24	More tape loads, much punching, remainder of tape loads
Directive tape*	black Sw.		Sets directive at end of new program tape

Output tape from above bootstrap 24 or SF If stop on 24 new tape okay, if stop on SF discard tape and repeat above

* This tape will read 00K26984Nd0 where d denotes a single delay.

3. Series of Production Runs using Hexadecimal Program Tape.

In this example, it is assumed that changes in the program are desired (such as perhaps the inclusion of the constant acceleration overwrite, etc.) which cause the sum check to be incorrect. It is also assumed that all DOI parameter changes are applicable to all runs and can hence be on the same tape with the code changes, this tape being marked "Master Parameters". To prepare "Restart" tape see Appendix K.

Tape	Start	Stop	Comments
Program	Bootstrap	24	Entire tape loads, Stop on SF instead of 24 means reader error-adjust reader(?) and reload.
Master Param.	White Sw.	24	Entire tape loads.
Run Param.	Black Sw.	4F	Memory sum check must be set after 2nd print.
Run Param.	White Sw.	24	End of run 1.
Run Param.	Black Sw.	24	End of run 2. Continue to repeat this step to end of parameter tape.

Notes to operator:

(1) If a 4F stop occurs (other than the one listed above after the second print), memory failure is indicated. In this case mark the "Run parameter" tape at the position which is under the reader, and repeat all of the above steps, except that when placing the run parameter tape under the reader, place it at the mark rather than at the beginning.

(2) If white switch stop other than 4F occurs, mark "Run parameter" tape at the position which is under the reader, bootstrap "restart" tape (no memory clear), reinsert "Run Parameter" tape at marked position and return to repeating of last instruction above.

Appendix B: Instructions for changing the number of machine sectors.

The number of machine sectors is stored as an integer in location 163(OK3₁₆), and is presently set at 3. If the absolute angular extent of each R-K step is left unchanged (i.e. if the number of R-K's per revolution remains constant) then the number of sectors can be changed to any desired value by simply changing the integer in 163. If it is desired to change the number of sectors and at the same time change the length of the R-K step, as for instance would be required if it was desired to retain the same number of R-K's per sector, than the changes described in Appendix C must be performed in addition to the resetting of 163 to the desired value.

Appendix C: Instructions for changing the angular interval per R-K step.

To change the angular interval per R-K step several constants, the table of cosines, and the location of the field storage must all be changed

The constants to be changed are the following:

Location	DOI format	
372	00["2 π "]F 00 F	"2 π " is integer equal to twice the number of R-K steps per revolution.
373	00 F 00[2 ^m $\Delta\theta$]J	where $\Delta\theta$ is the angular extent of an R-K step in radians. m is presently 2 and for maximum significance $1/2 \leq 2^m\Delta\theta < 1$.
297	10 m F 40 3F	where m is power of 2 by which $\Delta\theta$ is scaled (see above).
300	00 m F 40 3F	same.
375	00 "3 $\pi/2$ " F 00 F	"3 $\pi/2$ " is integer equal to 3/2 times the number of R-K's per revolution. (R-K's/ revolution must always be even number.)

The table of cosines begins in location 410 and must consist successively of the cosines of all integral multiples of $\Delta\theta/2$ from 0 thru $\pi/2$ inclusive ($\Delta\theta/2$ must be such that $\pi/2$ is integral multiple). $\Delta\theta$ as presently set in the program is $\pi/24$ so that the table presently consists of 25 values. Immediately after the table of cosines the field storage begins. If $\Delta\theta$'s smaller than $\pi/24$ are employed, the field storage must be shifted since the table of cosines will in this case require more than 25 locations.

The location of the field storage is set at the very beginning of the "Load B Routine" Program tape, the 8th word on this tape being an integer presently set at 435. In order to shift the field storage, it is necessary to prepare a revised tape with the 435 changed to the desired value - overwriting of the 435 after loading the program will not

suffice since the quantity is used as an "S box".¹

The total number of storage locations available for fields is of course decreased by just the amount by which the table of cosines is enlarged.

Appendix D: Use of Fictitious N.

In general as seen from Appendix C, a change in the angular length of the R-K step involves considerable revision of the code. In the special case where it is desired to triple the number of R-K steps per revolution in fields containing no imperfection components, a convenient trick can be employed as follows:

1. Prepare a special field parameter tape with $H=1$ and h = number of main field harmonics.
2. Prepare a special field data tape with zeros inserted in all H_1 , G_1 positions and with actual main field harmonics typed in the imperfection field position.
3. Change the constant $2^m \Delta\theta$ in location 373 to $1/3$ of its previous value.

After making these changes proceed to run in the usual manner. 48 R-K steps will be required to complete a sector and 144 to complete a revolution.

Whenever round off error is suspected of appreciably influencing the results of normal runs, this simple change by factor three in the number of R-K steps is a convenient procedure for obtaining an estimate of the extent of the error. Due to special features of the gap crossing routine, acceleration should not be included in such runs.

Appendix E: Acceleration Changes

The program, as written, approximates acceleration effects by increasing the kinetic energy of the particle at each of two arbitrary azimuths, the magnitude of the increase varying in the normal way as the cosine of the phase angle between particle and R-F as is indicated by eq. (6), Section I.

In many situations it is desirable to eliminate the phase factor from the acceleration thereby making acceleration constant at each gap (i.e. to use "square wave" acceleration). This is accomplished by the following change:

242: L5 11F 10 1F

To return to normal operation after constant acceleration operation:

242 50 F 7J 11F

The routine can also be caused to approximate betatron type acceleration, (i.e. the energy can be made to increase by the amount $\Delta K/2 \cos \phi$ at the end of every R-K step) by the change:

227: 22 232F L0 12F

Note that in this case ΔK is the maximum energy gain in 2 R-K steps rather than per turn. If desired this correction and the previous correction can be employed together to give "continuous constant acceleration". To return to normal operation after "continuous acceleration" operation:

227: L5 38F L0 12F

Appendix F: Providing additional field storage by omission of the special Input Routine.

As mentioned in the text, 90 additional field storage locations can be made available by leaving out the special input routine. To accomplish this for forward runs simply remove the program tape from the reader at the black switch stop which occurs near the end of this tape when loading. Substitute a DOI parameter tape and black switch. In this mode of operation all of the parameters in locations 4 thru 16 inclusive must be set on every run, since the master parameter routine is also omitted. The directive 26 401N at the end of the parameter tape will start the run.

To make backward runs in this mode the first of the backward runs must include the following code changes in the parameter tape:

```

137: 50      F  79      F
141: 50      F  7J      F
335: 50      6F  71      7F
339: 71      5F  66      28F
354: 40      30F  75      F
366: 7J      373F  40      28F

```

To revert to forward runs, following backward runs, the first of the forward runs must reset these orders by including in the parameters:

```

137: 50      F  7J      F
141: 50      F  79      F
335: 50      6F  75      7F
339: 75      4F  66      28F
354: 40      30F  71      F
366: 79      373F  40      28F

```


Appendix G: Runs with initial $\theta \neq 0$.

In normal operation, it is assumed that the $\theta=0$ angle of the magnetic field description is the angle at which orbits start i.e. the angle at which the initial conditions apply. If it is desired to start orbits at some other angle with respect to the field the following changes must be made in the program:

```

408: 92 135F 22 215F
215: 26 205F L5 216F
216: 50 [n]F 46 38F
217: 26 244F 19 13F

```

For forward runs "n" is set at twice the number of R-K steps between $\theta=0$ and the starting azimuth. For backward runs "n" is set to be the complement with respect to twice the number of R-K's per revolution of the forward "n".

The print counter operates independently of θ by simply counting the R-K steps actually completed. Prints will therefore always be spaced at equal R-K step intervals from the initial θ irrespective of the value of that θ .

Caution should be exercised in carefully labeling output from runs with $\theta \neq 0$, since the format is not readily distinguishable from other runs. (Actually the contents of the sum check cell do distinguish such runs in a disguised way, since the memory cells changed are included in the sum, and the sum will hence differ by the sum of the changes.)

To revert to normal operation after $\theta \neq 0$ runs reset as follows:

```

408: 92 135F 26 244F
215: 26 205F 00 F
216: 00 F 00 F
217: 00 F 19 13F

```

Appendix H: Suppressing $1/64\Sigma r$ in Code Output.

The quantity $1/64\Sigma r$ was originally included in the routine as a means of obtaining an average orbit radius to use in a later computation of an isochronous correction to the given field. Subsequently the Equilibrium Orbit Code giving the exact average of r has come into use and consequently the $1/64\Sigma r$ column in the general orbit code output is now seldom used.

This column can be omitted from the output by the following change:

```
265: 12 515F L5 10F
```

This change is especially desirable when making axial motion runs since as discussed in Section VII, the output line length for such runs with the $1/64\Sigma r$ included is such as to cause double spacing by the printer between lines thereby giving an excessively long piece of paper.

To return to normal operation after running without $1/64\Sigma r$ reset as follows:

```
265: 12 515F L5 11F.
```

Appendix J: To run with $\omega_{rf} \neq eB_0(0)/m_0$.

Since ω_{rf} is implicitly the basis of the system of field, length, and time units used in the code, it is necessary, in order to make runs corresponding to non-isochronous ω_{rf} 's, to numerically rescale the complete field and the unit of length. Let ω_0 be $eB_0(0)/m_0$. To run with $\omega_0 \neq \omega_{rf}$ perform the following steps.

(1) In the field parameters change the value of B_{cen} in volts by the factor ω_{rf}/ω_0 . (i.e. the new B_{cen} is now just $\omega_{rf}m_0/e$).

(2) Prepare a new data tape in which all B's, H's etc. are multiplied by the factor ω_0/ω_{rf} (i.e. the data on the new tape are now in units of $\omega_{rf}m_0/e$, as is required by the routine).

After making these changes proceed with the run in the normal manner.

Appendix K: Restarting the routine after a White Switch Stop.

Many of the overflow stops listed in Table I are not programmed in a manner such that operation can continue on to other runs without a special restart. When such a stop occurs in a sequence of runs and it is desired to continue to the next run in the sequence a "reset" tape containing the ten character word 92 0JL 22 10K should be bootstrap loaded with no memory clear. This operation will print a series of (((((followed by the same series of information as for an r too large or too small stop. The code will reset itself and stop on the normal end of run stop ready for the next parameters of the next run.

Appendix L: To change the Sector Number of the Imperfection Field Fourier Series.

From equation 6, section I it is seen that the imperfection field is implicitly assumed in the program to have only once per revolution periodicity. In some cases it is desirable to study imperfection fields with periodicity of 2 or more per revolution and if the format 6 is employed this requires that zeros must be inserted for the lower order harmonics of the imperfection. The following correction serves to insert a sector number in the imperfection field series in equation 6 in a manner exactly analogous to the sector number appearing in the main field series.

To insert a sector number other than unity in the imperfection field series load the following modification tape with the white switch after loading of the program tape.

```

00 167K
40 27F 50 38F
75 908F S5 ___F
40 28F 26 906F
00 906K
L5 908F 00 32F
40 26F 22 159F
00 F 00 pF p is number of sectors in imperfection
26 977N field.
```

This correction uses three locations normally set aside for field storage and therefore when it is used the number of field values must be ≤ 473 .

Appendix M: To Change Scaling of Field Derivatives. "Entry Interlude"

The maximum value of the field derivatives depends sensitively on the characteristics of the particular field. The code is of course protected against overflow of these quantities by stops in the Fourier Series routine - if these stops occur and it is still desired to study the particular field it is necessary to change the scaling of the field derivatives.

To accomplish a change in scaling load the following tape with the white switch after loading of the main program tape.

```

00 33K
L5 6L 42 221F
L0 5L 46 342F
42 168F L5 3L
50 41F L0 6L
46 183F 26 977F
00 1F 00 3F
00 nF 00 nF derivatives scaled by 2-n
26 33N

```

The main program, as written, has derivatives scaled by 2^{-7} . Hence if overflow stops occur and the above modification is employed values of n greater than 7 should be tried. To maintain significance it is desirable to use the smallest value of n which will prevent overflow; a few trial searches should therefore be made to determine the proper value of n for use with a particular field.